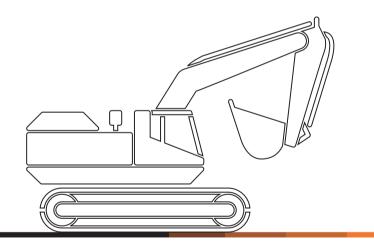
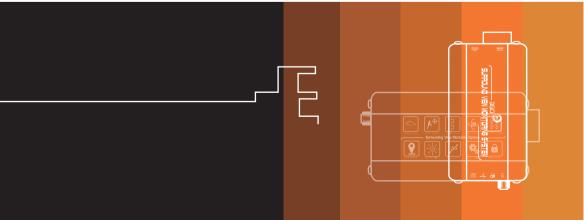
## Surround View Monitoring System







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## Safety Tips

Please read this manual carefully before using and pay attention to this section for the safety Instructions.



Serious traffic accidents may be caused by keeping watching on the screen or operating the system during driving. It is strong recommended that do not operate this system while driving.

SVM is a parking and driving assistant system which offers the road situation around the vehicle to eliminate blind spots and thus works perfectly as a visual guide for safe parking and driving. It may bring inconsistence between the screen image content with actual surroundings of the vehicle. Please handle this case according to actual situation.

Never hotplug the host device when power is connected. The host device can't be sinked in any kind of liquid. Please kindly pay attention to heat dissipation. Please contact professional installation service providers in case of any abnormal situations.

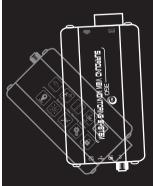
## **Brief Introduction**

## Guide

This guide is to provide the basic illustration for topological structure of the SVM system, operating principle and basic concept to help users to understand the whole system installation procedure, camera calibration steps, and how to interact with the system menu.

#### Brief Introduction of System

The SVM 3D Around View Monitoring Technology synthesizes images from four cameras to create a true 3D sophisticated view of a vehicle's surroundings. The technology enables flexible omni-directional monitoring around a vehicle from a dynamically definable perspective or "free eye point." Such kind of technology can display the complete vision of the positioning and moving path of the vehicle, it covers blind spot and thus works perfectly as a safe parking and driving guide even when restricted by adjacent vehicles and objects, parking line, etc. The system offers various SVM system configurations like -HDMI/LVDS/AV with alternative version of 2D or 3D, and what's more, this system also integrated four channel car DVR function with 24 hours videos loop recording supported.



## **Product Features**

#### Product Features

Four 190 degrees ultra wide fish-eye cameras

Seamless video merging based on dual core ARM CPU and hardware high efficiency acceleration engine.

Arbitrary and dynamic 3D mode view angle switching for better surrounding environment observation

Independent Fish-eye calibration parameter and algorithm for each camera.

Pixel statistic engine for realfime brightness balance among four channels outside cameras.

3D video de-interlacing and noise reduction technology for CVBS signal decoding.

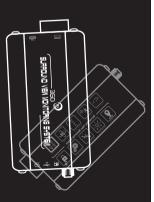
Support alternative recording media for TF card or USB disk

The simplest calibration steps with calibration tape and packing box, and system applicable for almost all types of vehicle which including Buses, Trucks, Lorries, Limousines, Tanksand even Jumbo Jets. Typical length of the vehicle is 5.5m, 6.5m, 10m&13m.

Smart power managements to save automobile's battery

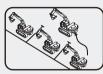
High video recording resolution up to 1440\*960.

OE quality for main chipset with well protected circuit and devices in order to achieve the best system performance and stability.



# Product Features

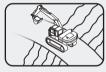
## Main application scenarios



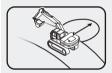


Reverse Parking

Side Parking



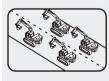
Narrow Road/Lane

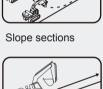


Blind Spots Coverage

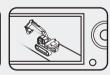


Security&Surveilance





Turning assist



Car DVR

#### Crowed Road

#### Features Profile

3D & 360° Seamless Merging 360° Blind Spots Coverage Dynamic & Intelligent View Angle Switching Flexible Omni-directional Monitoring Exclusive Fish-eye Distortion Correction Guided Camera Calibration

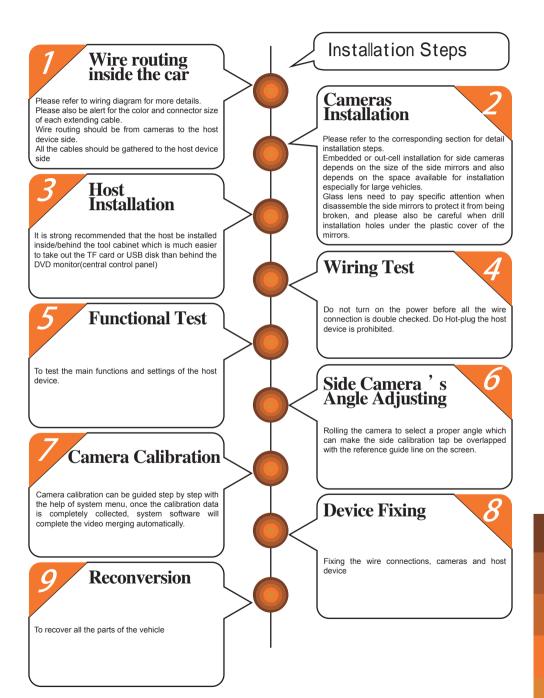
#### Optional Function

- a.Driving Video Recording b.24 Hour Parking Monitoring
- c.G-sensor Triggered Recording
- d.Visual Radar Extension

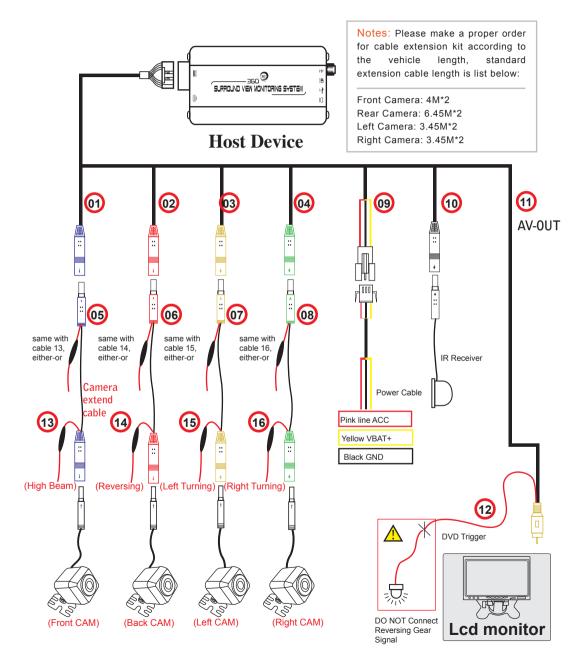
#### Note

This manual gives a basic and general feature description of the system, but it may vary from specific product model and application case. Please consult sales team for detail specifications before ordering.

#### **System Hardware Installation**

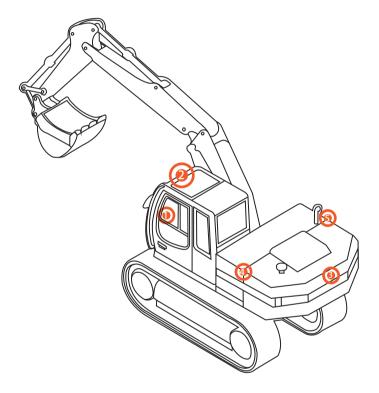


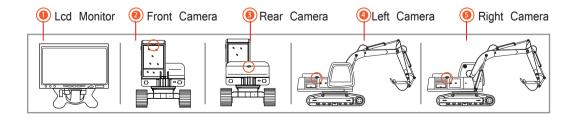
## Wiring Diagram



## Cameras Location For Excavator

Perspective Drawing

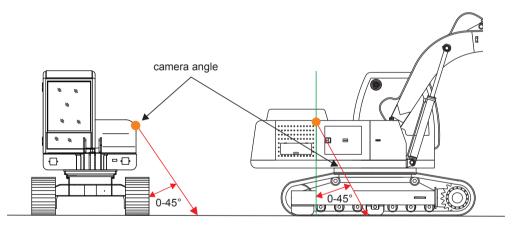




## **Cameras Installation Angle For Excavator**

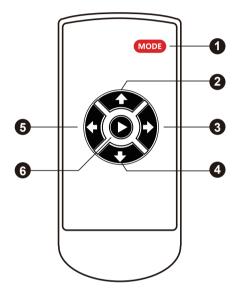
Please keep in mind that choosing a proper camera installation position to get as many pixel contents as possible while keeping the body of the vehicle visible. The camera optical axis should keep a vertical angle of 45 degree appropriately corresponding to vehicle body. For excavator camera installation, it is strong recommended to install all the cameras in the middle point of each top side which illustrated as follows:

#### Camera Installation Angle For Excavator



## **Remote Controller Introduction**

#### Perspective Drawing



Key Number	Description	Function	
		Enter Setting Menu	
[1]	MODE	In SVM Mode, long press 2 seonds enter into 4CH recording mode	
[2]	In Menu menu, select last menu option		
[2]	0F	In SVM Mode, short press enter high beam mode, press again back to SVM mode	
[3]	RIGHT	In SVM model, long press enter into right 360 rotatable mode	
[4]	[4] DOWN In SVM mode, long press enter into reversing gear mode		
[4]	DOWN	In menu setting, select next menu option	
[5]	LEFT	In SVM model, long press enter into 360 rotateable mode	
[6]	Confirm	Confirm selected option	

## **Host Device Installation**

#### Host Device Installation Steps

**1**.Disassemble the panel of central control unit, and connect the reversing video channel of Lcd monitor or other display screen(AV in).

**2.** The host control unit installation:

**IR Mode:** Put the infrared receiver in a proper position.

**3.** Please connect the anode of the left/right turning signal from the fuse box to host wire harness, or from side mirror turning LED indicator to the camera side of the extending cable.

**4.** Connect the power cable to batter supplier line and connect the wire harness to the host device.

**5.**Fix the host device in the tool cabinet or the space behind the central control panel.

**6.**Connect all the cables for the coming function testing and debugging procedure, and assemble the panel back to the control unit.



## **Camera Calibration**

#### Calibration Parameters Setting





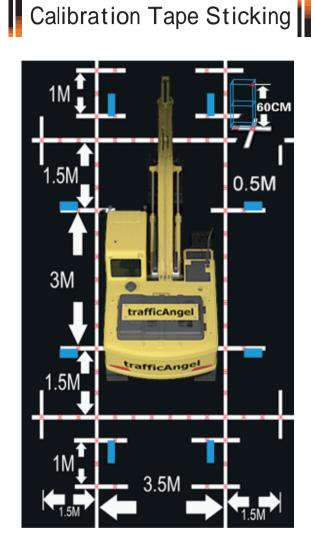




First of all, please short press the "MODE" button on the remote controller enter system menu settings.

Second, please select the correct calibration size for the applied vehicle model, set the shadow area and each step of the shadow setting is 5cm, please keep it as the default if you are not sure with the sensor type.

## **Camera Calibration For Excavator-I**



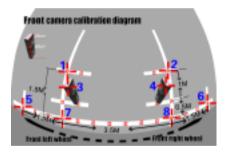
Note:

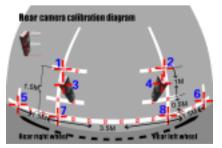
As the menu diagram shows, pasting the calibration tape around the vehicle. Please refer to the calibration pictures of different vehicle models and sizes to select the correct one for matching your vehicle.

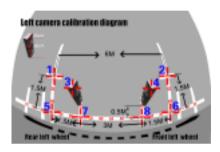
## **Camera Calibration For Excavator-II**

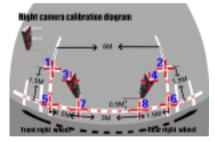
## Placing Packing Box

There are always 8 calibration points for each camera which need to be marked in the screen, the third pixel point and forth calibration point are always special points which are actually the diagonal corner of the packing box. The packing boxes can be divided into outer and inner one so that each packing box can be used for calibration 1 camera each time.







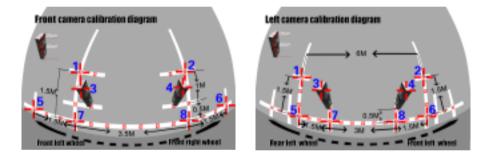


**Notes:** Put the 3 packing boxes in the correct position separately as the pictures above illustrated. You can also use other boxes instead as a calibration reference objects, the dimension requirements of the box must be 90cm in height.

## **Camera Calibration For Excavator-III**

#### Calibration Points Marking

You can start calibrating the four cameras one by one when the cursor is twinkling. Moving the cursor to the corresponding locations by the remote controller buttons of up/down/left/right, then press the "ok" button to mark the current calibration point in the screen and then the system menu will guide you to the next calibration pixel point in order from 1 to 8 one by one, please see the correct location and sequence of the calibration points as bellow pictures:



Press the red "Mode" button to toggle to previous calibration point selection when needed.

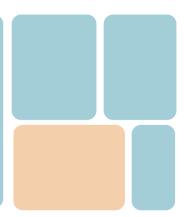
**Notes:** The calibration locations of No.7 calibration pixel point and No.8 calibration pixel point between the front&rear cameras and the sides cameras are totally different. The more accurate calibration points you mark, the better quality of the panoramic image merging will be.

## **Camera Calibration**

## Merging Calculation

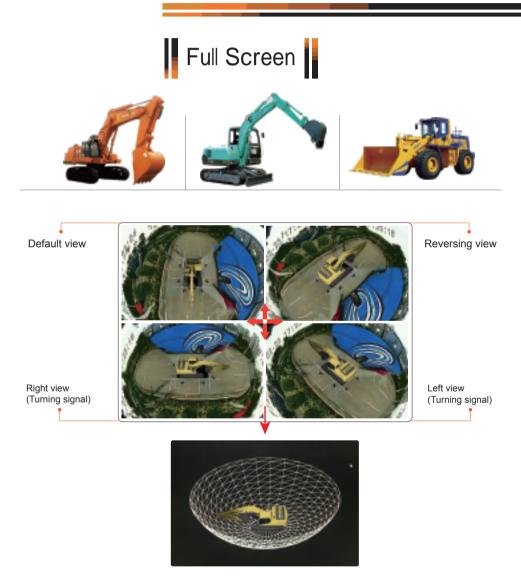


Press "OK" to start image merging. Do not shut down during this operation, System will reboot automatically after image merging finished.



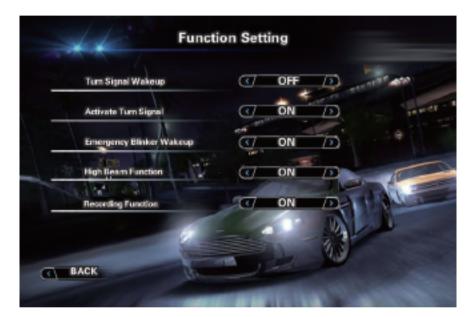


#### 3D Full Screen Display Mode





#### Parameters Setting and Menu Description



Menu Item	List Options	Description	
Turn Signal Trigger	ON/OFF		
Activate Turn Signal	Activate Turn Signal ON/OFF When the SVM is going to standby mode, th control whether the SVM system can be turning signals.		
Emergency Blinker Trigger	ON/OFF	When the SVM is going to standby mode, this option is use to control whether the SVM system can be activated from Emergency Blinker, and you can also use Emergency Blinker to set it back to standby mode again when this option is set to ON.	
High Beam Function	ON/OFF		
Recording Function ON/OFF		This is also a global switch to control whether the recording function is ON or OFF.	

# **Interface Settings**

Language Setting	English D
Vehicle Brand Setting	(* Vehice Type 1/)
System Mode Setting	(T) Ful Screen (S)
Screen Position 1 4	
Screen Position	Î D

Menu Item	List Options	Description
Language Setting		
Vehicle Brand Setting		
System Mode Setting		
Screen Position Up/Down		Screen TCON horizontal front porch and back porch control.
Screen Position Left/Right		Screen TCON vertical front porch and back porch control.

# Upgrade & Restore



Menu Item	List Options	Description
Restore Defaults	Default/ User Preference	Default is not functional at this moments, and choose user preference to restore user preference of video settings/win- dow configurations etc.
Upgrade Options	Default / Upgrade 3D Mode / Upgrade All / Import Calibration Data / Export Calibration Data	
Version Information		
Permission Setting	Default	
Reserved Menu	Default	

# **Other Settings**



Menu Item	List Options	Description
Hazard Blinker Trigger Duration	30S/1Min/ 3Min/5Min/	
Display Turn Delay		
Trigger Delay0S/3S/5S/ 10S/30SScreen saver trigger		Screen saver mode after turnning/reversing trigger
Reversing/Turning Trigger Duration 0S/3S/5S		This option is similar as Emergency Blinker Wakeup Duration, you can adjust the duration time for Turning/Reversing signal here also.
Standby Duration 0H/0.5H/1H/3H/ 5H/12H/24H		
Vibration Sensitivity	Low/Medium/High	After ACC is off in 1 minute, System will Enter standby mode and record if detect collision and vibration.

Video Settings

Menu Item	List Options	Description	Video Setting
Saturation			(Cronto
Brightness	-9~+9	Adjust input video brightness	
Contrast			
Sharpness			
Reserved Rod Setting			

#### Video Recording Functions

1. Long press "Mode" button to switch to recording system menu.

2. Press the "OK" button to stop current recording.

3. Using "Up/Down" button to navigate between recorded files as per date and timeline.

4. Press "OK" button again if the current recording file is just the right one you want to playback, and you can enlarge any of the 4 cameras to full screen mode by pressing left /right/up/down Button.



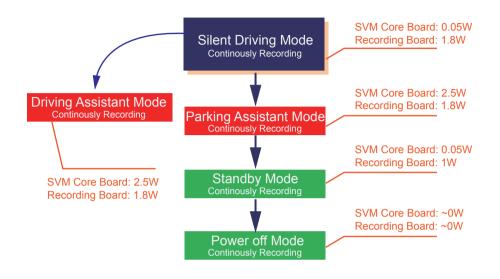


### **Basic Settings**

Ξ.		•	88:44
Θ	Pate		
0	Language	Eng	plish 💙
0	Time WaterNask		$\checkmark$
₿	Format	Format SD	card 💙
0	Factory Reset		
(j	Firmware Info	8SB.r2	2.8-3.13

Menu Item	List Options	Description
Date		Change system time
Language	English/Chinese	
		Format the TF Card or USB Disk
Factory Reset		
Firmware Info		

## Smart Power Management Strategy



#### Silent Driving Mode

Silent Driving Mode is the most frequency used while driving, the recording system will continuously take the outside video and record the compressed video on the recording media such as TF card or USB disk. Note that USB disk have a higher priority over TF card.

#### Driving Assistant Mode Parking Assistant Mode

During this mode, maximum power is expected to consume, since both the recording board and SVM core board is full functional. But this mode will never last for a long time, driving assistant mode is usually last for several seconds, and parking assistant mode usually work for 1~2 mins.

#### Standby Mode

At this mode, the recording system is standby, and if any vibration is detected by the G-sensor, our SVM system will power up the external Cameras and LEDs immediately and start video recording.

#### Power Off Mode

The system is power off except for the Real Time Clock chip and G-sensor, and the whole system is also capable to awake from the vibration events. But under some special case such like the battery is lower than 11V, and system will never be awaked except for the event of engine start.

# **Packing List**

### Packing List



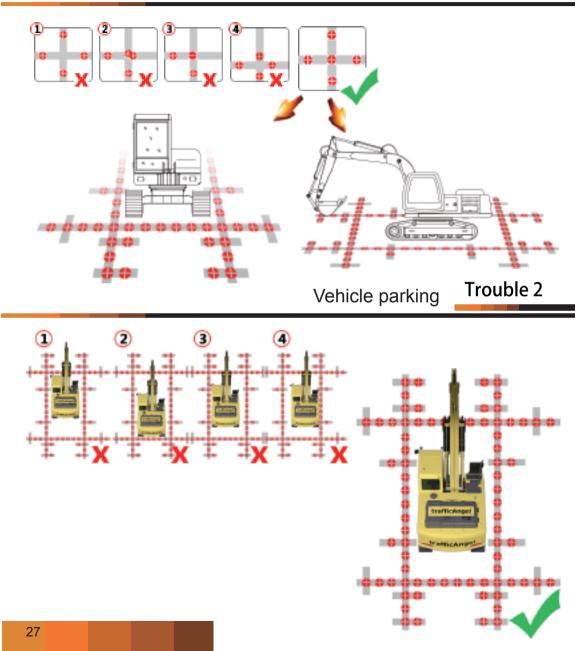
# Specification

### Datesheet

Туре	Specification	
	Video Interface	Mini plug connector
	Input / Output Impedance	75Ω
	Amplitude	Typical 1Vpp, 1.2Vpp Maximum
Video	Bandwidth	8MHz
VIGEO	Sampling Frequency	13.5MHz
	DP(Differential Phase)	<0.8° TYP
	DG(Differential Gain)	<3%TYP
	SNR	70dB
la dia atau kanan	High beam	Optional
Indicator Lamp /Blinker	Left/Right Turning Blinker	Yes
/ Dill Kei	Reversing Lamp	Yes
G-sensor	BM250E	Bosch
	Algorithm	H.264 Baseline@L3.1
Compression	Resolution	1440*960@30fps
Compression	Bitrates	5Mbps, 3Gbyte/Hour
	Recording Media	USB Disk(High Priority)/TF
	TF CARD	32G SDIO3.0/SDIO2.0
Disk Capacity	USB Disk	128G USB2.0
	4-CH DVR + SVM mode	600mA
Power Consumption	4-CH DVR mode	440mA
	Sleep Mode	<10mA
Dimension	L*W*H	123*81*25mm(Host Metal box)
Weight		220g
	Normal Working	–20℃~+85℃
Environments	Storage	–40℃~+105℃
	Relative Humidity	0~95%
Voltage Tolerance	Working Voltage	9.5V~36V

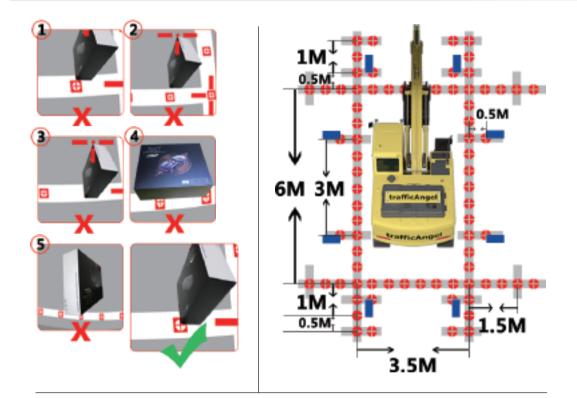
# **FAQ**

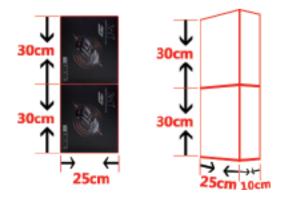
Paste the calibration tape Trouble 1

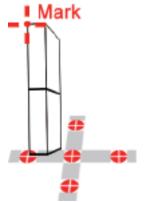


# FAQ

Trouble 3 Put the gift boxes

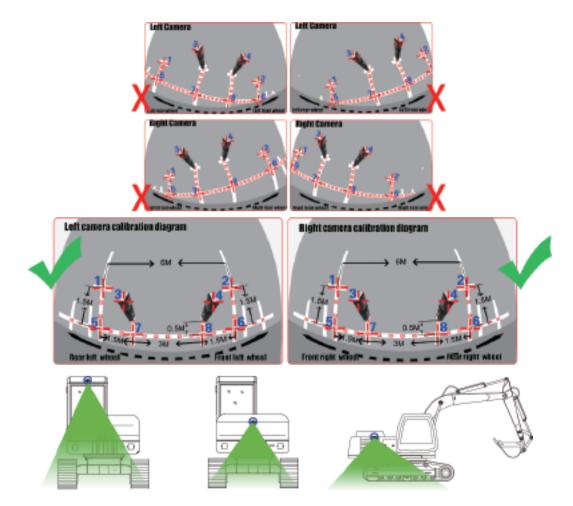








#### Adjusting camera angle & Mark calibration points Trouble 4



The camera axis should keep avertical angle of 45° appropriately with vehicle body. with the help of guided preview window provided in system software menu, please keep in mind to keep the whole cabibration tape and all 8 calibration points visible while keep as many pixel as possible.

## **Service Promise**

As a leading R&D enterprise in the Automobile industry, we are committed to engineering and manufacturing our products to the highest standards of quality, performance, and value. From our advanced product design, manufacturing and quality control procedures to our



friendly and knowledgeable support teams, our commitment to satisfy you is paramount. In every interaction with us, you can be confident you will receive our commitment to Service, Support, and Solutions. For 7 years, our objective has been to ensure that every customer is completely satisfied with every purchase. To underscore this commitment, we offer our Satisfaction Guarantee. This means we will work diligently to resolve any issue you have with your purchase until you are completely satisfied. Our employees are prepared to do whatever it takes to make certain that the entire process of doing business with us is a positive and professionally rewarding experience for you. We greatly appreciate your business. It is our intent to keep you as a customer for life.

